

Mean Field Games in Macroeconomics

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Motivation

- Modern macro needs tractable GE models with **aggregate** and **idiosyncratic** uncertainty

- Given individual state $x_i \in \mathcal{X}$ and the distribution of agents $g \in \mathcal{P}_2(\mathcal{X})$, solve

$$V(x_i, g) = \max_{\alpha \in \mathcal{A}} \left\{ u(\alpha, x_i, g) + \beta \mathbb{E}^{i, g} [V(x'_i, g')] \right\} \quad \text{s.t.} \quad x'_i \in \Gamma_x(\alpha, x_i, g)$$

- Distribution evolves as $g' \in \Gamma_g(g)$ – still an ∞ -dimensional object
- Krusell and Smith (1998): assume **approximate aggregation** and solve numerically
- **Can mean field game theory do better?**

Mean field games — background

- Formalized by Lasry and Lions (2006): limit of N -player games as $N \rightarrow \infty$
- Framework for systems with many rational, symmetric players
- **Key insight:** equilibrium reduces to a system of PDEs
 1. Idiosyncratic shocks: reasonably well understood
 2. **Common noise:** much less is known
- Achdou et al. (2022): heterogeneous agent models can be cast in this form

Two equations at the core:

1. **Hamilton-Jacobi-Bellman** — optimal behavior of agents
 - Solved backward: given the future, what is optimal today?
2. **Kolmogorov Forward** — evolution of the density of agents
 - Solved forward: given optimal behavior, how does the distribution evolve?

Finding an equilibrium = finding a fixed point of the coupled HJB–KF system.

Standard MFG: Bewley-Aiyagari in continuous time

The household problem

- Consumer with income process $\{y_t\}$ chooses consumption $\{c_t\}$ to maximize

$$\mathbb{E} \left[\int_0^{\infty} e^{-\rho t} u(c_t) dt \right]$$

subject to

$$da_t = [ra_t + y_t - c_t] dt, \quad a_t \geq -\phi$$

- Income y follows a two-state Poisson process with intensities λ_1, λ_2
- Consumer takes the interest rate r as given

Stationary equilibrium as an MFG system

1. **HJB** + state constraint boundary condition (SCBC):

$$0 = \sup_c \left\{ -\rho v_j(a) + u(c) + v_j'(a)(ra + y_j - c) + \lambda_j(v_{-j}(a) - v_j(a)) \right\}$$

$$v_j'(-\phi) \geq u'(-r\phi + y_j), \quad j = 1, 2$$

2. **Kolmogorov Forward**:

$$0 = -\frac{d}{da} [s_j(a) g_j(a)] - \lambda_j g_j(a) + \lambda_i g_i(a)$$

3. **Market clearing**:

$$\int_{-\phi}^{\infty} a [g_1(a) + g_2(a)] da = 0$$

Understanding the state constraint

Following Soner (1986): assume a continuous optimal policy $c^*(a)$ and differentiable v .

1. The borrowing constraint requires $r\underline{a} + y_j - c^*(\underline{a}) \geq 0$
2. Optimality of c^* gives $H_j(\underline{a}, v'(\underline{a})) = u(c^*) + v'(\underline{a})(r\underline{a} + y_j - c^*)$
3. For any $\gamma \geq 0$:

$$H_j(\underline{a}, v'(\underline{a}) + \gamma) \geq H_j(\underline{a}, v'(\underline{a})) + \gamma(r\underline{a} + y_j - c^*(\underline{a})) \geq H_j(\underline{a}, v'(\underline{a}))$$

4. Convexity of H in p yields the equivalent condition

$$\partial_p H_j(\underline{a}, v'(\underline{a})) \geq 0$$

Intuition for the Kolmogorov Forward equation

- With time dependence:

$$\frac{\partial g_j(a, t)}{\partial t} = -\frac{\partial}{\partial a} [s_j(a)g_j(a, t)] - \lambda_j g_j(a, t) + \lambda_i g_i(a, t)$$

- Poisson terms (λ_j, λ_i): mass flows between income states
- Transport term: if $s > 0$ at a , mass flows rightward
 - Gain from $s_j(a - \epsilon)g_j(a - \epsilon, t)$, lose $s_j(a)g_j(a, t)$
 - Same expression regardless of sign of s – hence the divergence form

Application: impulsive MFG with lumpy investment

Firms with lumpy capital and convex labor adjustment

- Firms produce $y_t = f(k_t, l_t)$, taking r and w as given
- Without adjustment, capital depreciates:

$$dk_t = -\delta k_t dt + \sigma dB_t$$

- Capital adjustment is **lumpy**: jumping from k to $k + i$ costs

$$\mathcal{G}(i) = F + p^+ i^+ + p^- i^-$$

- Labor adjustment is **convex**: hiring at rate n_t costs $\mathcal{C}(n_t, l_t)$

$$dl_t = [n_t - \rho l_t] dt$$

- This gives a **combined stochastic control and impulse control** problem

The HJBVI equation

- Define the intervention operator:

$$\mathcal{M}v(k, l) := \sup_i \{v(k + i, l) - \mathcal{G}(i)\}$$

- The value function solves the **Hamilton-Jacobi-Bellman Variational Inequality**:

$$0 = \max \left\{ \sup_n \left\{ -rv + \pi(k, l, n) + \partial_l v [n - \rho l] + \partial_k v [-\delta k] + \frac{\sigma^2}{2} \partial_{kk} v \right\}, \mathcal{M}v - v \right\}$$

- Interpretation: optimal stopping with endogenous stopping value
- Extends standard MFG to settings with both continuous and discrete adjustments

Numerical strategy

Solve as a sequence of optimal stopping problems:

1. Compute no-intervention value v^0 from standard HJB:

$$0 = \sup_n \left\{ -rv^0 + \pi + \partial_l v^0 [n - \rho l] + \partial_k v^0 [-\delta k] + \frac{\sigma^2}{2} \partial_{kk} v^0 \right\}$$

2. Define v^j inductively as the solution to control + stopping:

$$0 = \max \left\{ \sup_n \{ \dots \}, \mathcal{M}v^{j-1} - v^j \right\}$$

3. **Convergence:** $\lim_{j \rightarrow \infty} v^j(k, l) = v(k, l)$

[Øksendal and Sulem 2007]

Implementation: finite differences + upwind scheme for HJB; linear complementarity for stopping.

Inaction region

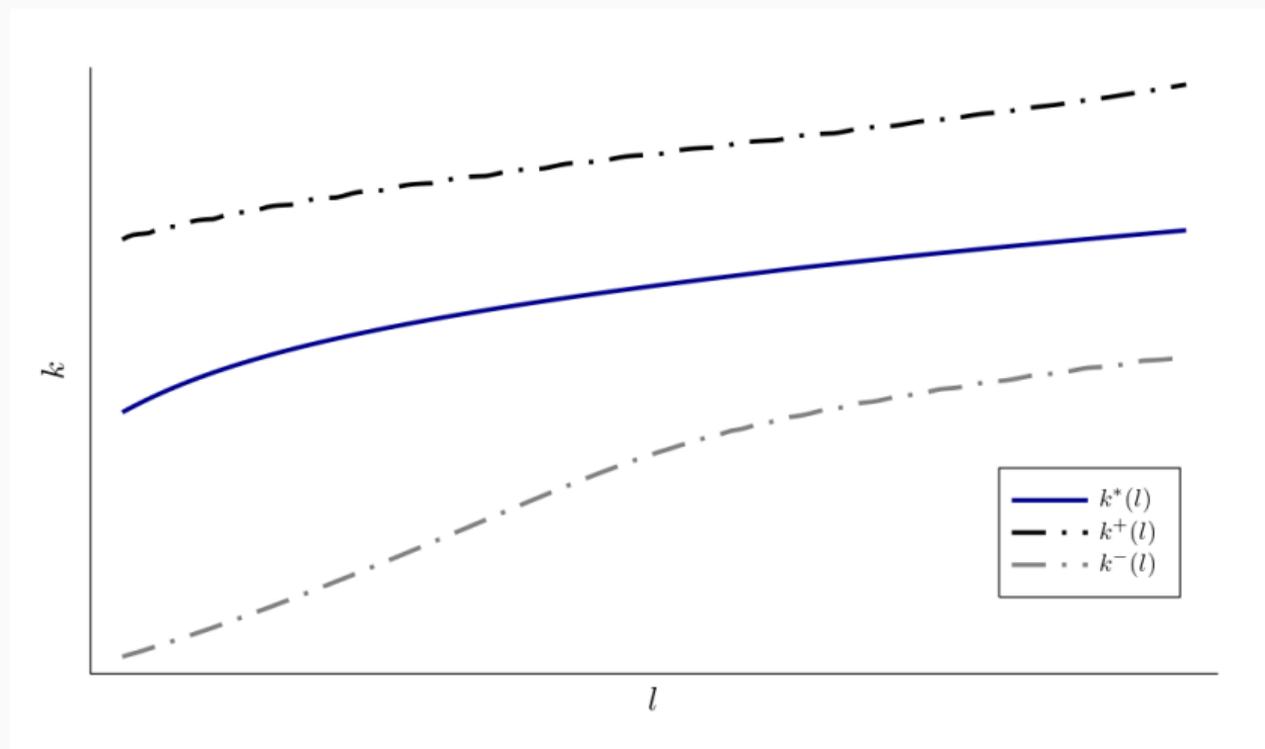


Figure 1: Inaction region in the (k, l) space — firms adjust capital only outside this region

Inaction region with irreversibility

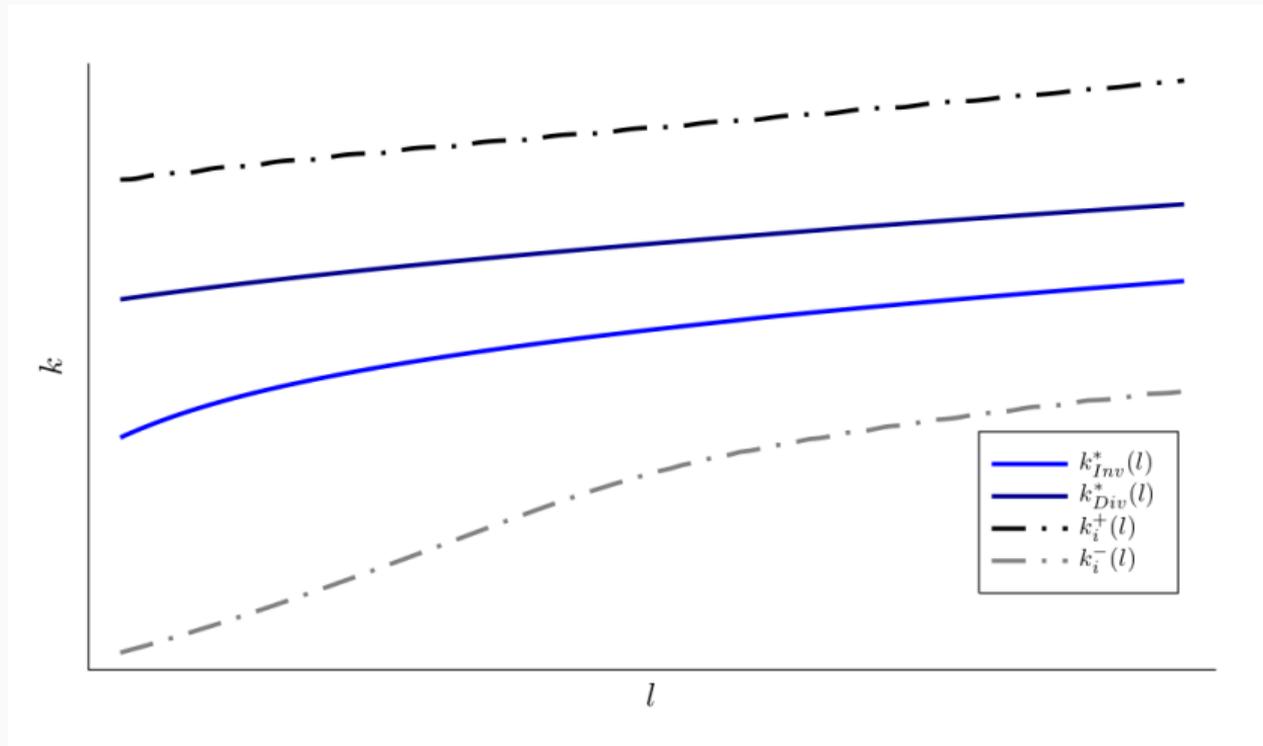


Figure 2: Asymmetric adjustment costs shift the inaction region

Equilibrium distributions

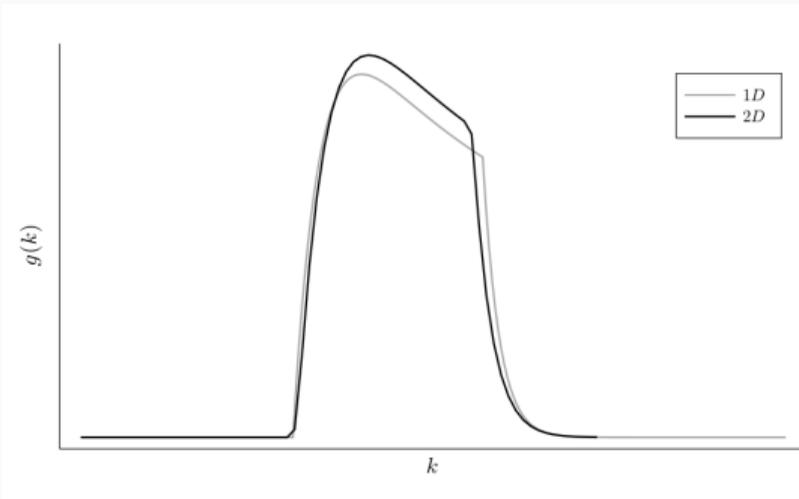


Figure 3: Capital distribution

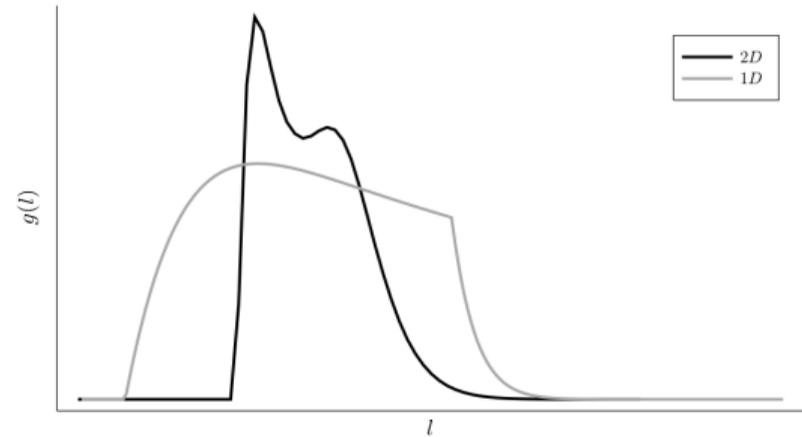


Figure 4: Labour distribution

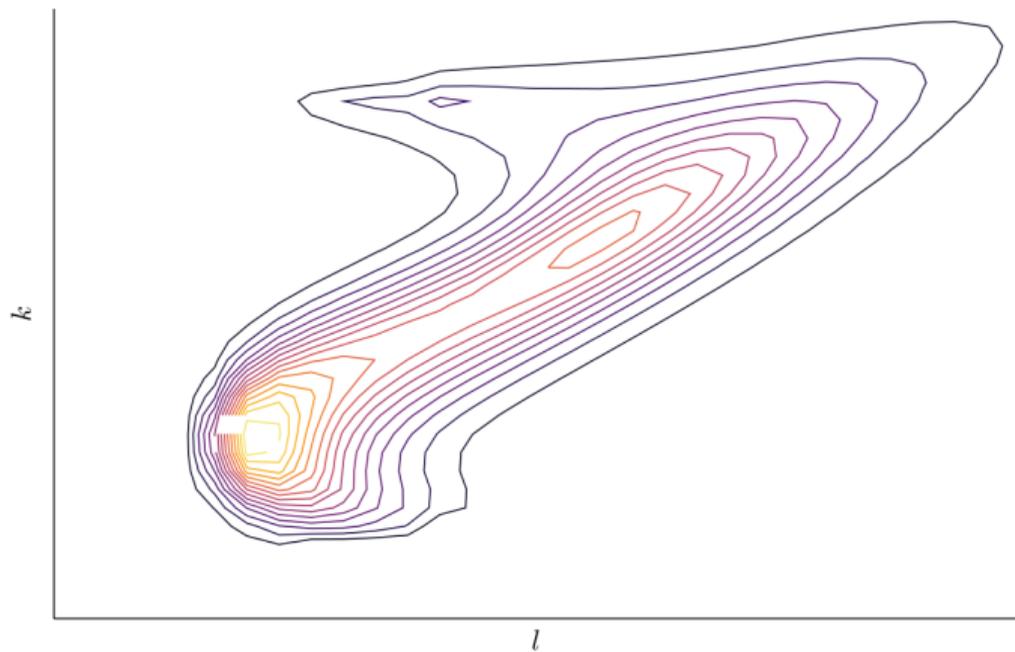


Figure 5: Joint distribution in the baseline model

General equilibrium

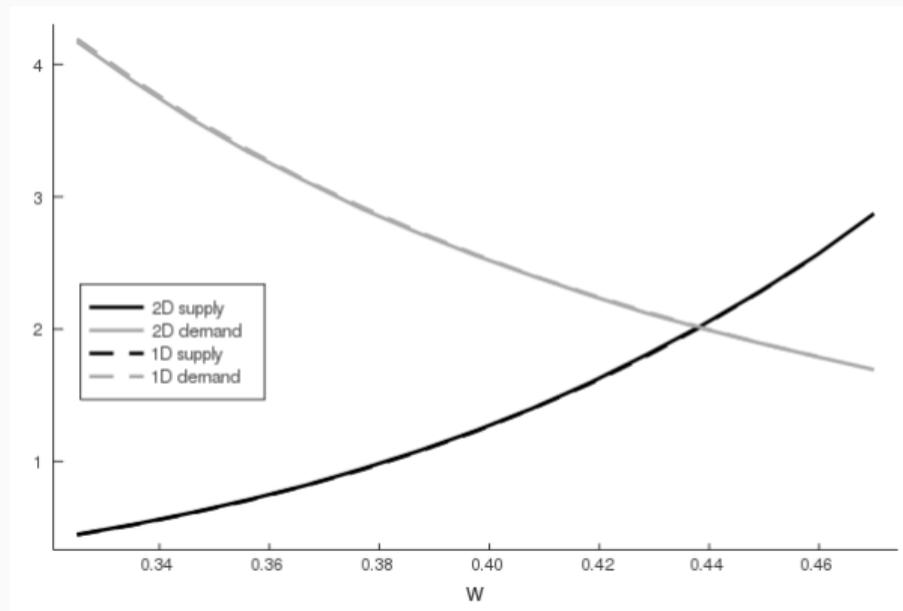


Figure 6: Equilibrium in the labour market

Outlook

Open directions

- **Aggregate shocks** \implies the Master equation
 - Bilal (2023): perturbation of the Master equation (FAME) reduces to a standard Bellman equation
- **Beyond the continuum:** MFG with major and minor players
- **Comparative advantage of MFG:** when GE enters individual problems beyond a small set of prices and the Krusell and Smith (1998) strategy breaks down
- **Machine learning for MFG:** neural networks as solvers for HJB–KF systems
 - Ruthotto et al. (2020): deep learning framework for high-dimensional MFG and MFC
 - Han et al. (2021): DeepHAM — global solution for HA models via neural nets
 - Payne et al. (2024): deep learning to solve Extended Master Equations in search models

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